



# Developing models with gem5

---

An overview of how to create models  
with gem5, debugging, and event-  
driven programming

# A simple SimObject

[https://www.gem5.org/documentation/learning\\_gem5/part2/helloobject/](https://www.gem5.org/documentation/learning_gem5/part2/helloobject/)

# gem5's coding guidelines

Follow the style guide ([http://www.gem5.org/Coding\\_Style](http://www.gem5.org/Coding_Style))

Install the style guide when scons asks

Don't ignore style errors

Use good development practices

*git branches*

One branch for each “feature”

# Adding a new SimObject

Step 1: Create a Python class (SimObject description file)

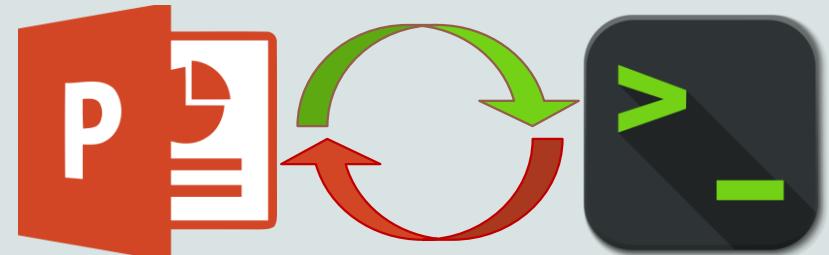
Step 2: Implement the C++

Step 3: Register the SimObject and C++ file

Step 4: (Re-)build gem5

Step 5: Create a config script

**Switch!**



# Step 1: Create a Python class

## HelloObject.py

```
from m5.params import *
from m5.SimObject import SimObject

class MySimpleObject(SimObject):
    type = "MySimpleObject"
    cxx_header = "tutorial/my_simple_object.hh"
    cxx_class = "gem5::MySimpleObject"
```

**m5.params:** Things like  
MemorySize, Int, etc.

Import the objects we need

**type:** The C++ class name

**cxx\_class:** The fully qualified  
C++ class name

**cxx\_header:** The filename for the  
C++ header file

## Step 2: Implement the C++

### hello\_object.hh

```
| #include "params/HelloObj.hh"  
| #include "sim/sim_object.hh"  
| class MySimpleObject : public SimObject  
| {  
|     public:  
|         PARAMS(MySimpleObject);  
|         HelloObj (const Params &p);  
|     };
```

**PARAMS** is a macro to convenience to `typedef Params` for this object

params/\*.hh generated automatically. Comes from Python SimObject definition

Constructor has one parameter, the generated params object. Must be a **const reference**

## Step 2: Implement the C++

### hello\_obj.cc

```
#include "tutorial/my_simple_object.hh"
MySimpleObject::MySimpleObject(const Params &params)
    : SimObject(params)
{
    std::cout << "Hello World! From a SimObject!" << std::endl;
}
```

**HelloObjectParams:** when you specify a **Param** in the Hello.py file, it will be a member of this object.

# Step 3: Register the SimObject and C++ file

## SConscript

```
| Import('*')
| SimObject('MySimpleObject.py', sim_objects=['MySimpleObject'])
| Source('my_simple_object.cc')
```

**Source()**: Tell scons to compile this file (e.g., with g++).

**sim\_objects**: The SimObjects declared in the file (could be more than 1)

**Import**: SConscript is just Python... but weird.

**SimObject()**: Says that this Python file contains a SimObject. Note: you can put pretty much any Python in here

# Step 4: (Re-)build gem5

## Step 5: Create a config script

```
| import m5  
| from m5.objects import *  
  
| root = Root(full_system=False)  
| root.hello = MySimpleObject()  
  
| m5.instantiate()  
| exit_event = m5.simulate()  
| print(f"Exiting @ tick {m5.curTick()} because"  
|       "{exit_event.getCause()}")
```

All simulations  
require a **Root**

Instantiate the new object that  
you created in the config file  
(e.g., simple.py)

**Instantiate** all the SimObjects  
(create the C++ instances)

**Simulate** the system as  
configured!

> build/X86/gem5.opt configs/hello.py

...

Hello world! From a SimObject!

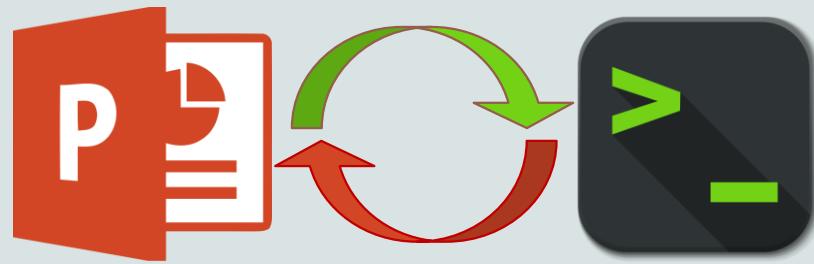
...

# Debug support in gem5

*[https://www.gem5.org/documentation/learning\\_gem5/part2/debugging/](https://www.gem5.org/documentation/learning_gem5/part2/debugging/)*

# Adding debug flags

## Switch!



# Adding debug flags

## SConscript

```
DebugFlag('MyHelloExample')
```

**Declare the flag:** add the debug flag to the SConscript file in the current directory

## hello\_object.cc

```
DPRINTF(MyHelloExample, "Created the hello object");
```

**Debug string:** Any C format string

**DPRINTF:** macro for debug statements in gem5

**MyHelloExample:** the debug flag declared in the SConscript. Found in “debug/MyHelloExample.hh”

# Debugging gem5

```
> build/X86/gem5.opt --debug-flags=MyHelloExample configs/tutorial/hello.py  
...  
0: root.hello: Hello world! From a debug statement
```

**debug-flags:** Comma separated list of flags to enable. Other options include  
--debug-start=<tick>,  
--debug-ignore=<simobj name>,  
etc. See gem5.opt --help

# Event-driven programming

*[https://www.gem5.org/documentation/  
learning\\_gem5/part2/events/](https://www.gem5.org/documentation/learning_gem5/part2/events/)*

Copy the template from materials/Developing gem5 models/03-events

# Simple event callback

```
| class MyHelloObject : public SimObject  
| {  
|     private:  
|     ...  
|     void processEvent();  
|     EventFunctionWrapper event;  
|  
|     public:  
|     ...  
|     void startup() override;  
| };
```

**EventFunctionWrapper:**  
Convenience class for simple events.

**processEvent:** Callback function to run when event fires.

**startup:** Called after all SimObjects instantiated.  
Schedule local events here.

# Simple event callback

```
| void
| MyHelloObject::processEvent()
| {
|     timesLeft--;
|     DPRINTF(MyHelloExample, "Hello world!"
|             " Processing the event! %d left\n", timesLeft);
|     if (timesLeft <= 0) {
|         DPRINTF(MyHelloExample, "Done firing!\n");
|     } else {
|         schedule(event, curTick() + latency);
|     }
| }
```

**schedule:** Put an event instance on the event queue. An absolute tick used for when the event is processed.

**curTick:** Returns the current simulator time. Useful for relative time computations.

# SimObject parameters

*[https://www.gem5.org/documentation/  
learning\\_gem5/part2/parameters/](https://www.gem5.org/documentation/learning_gem5/part2/parameters/)*

# Adding parameters

```
class MyHelloObject(SimObject):
    ...
    time_to_wait = Param.Latency("Time before firing the event")
    number_of_fires = Param.Int(1, "Number of times to fire the event before "
                                  "goodbye")
```

**Param.<TYPE>**: Specifies a parameter of type <TYPE> for the SimObject

**Param.<TYPE>()**: First parameter: default value. Second parameter: “help”

# Adding parameters

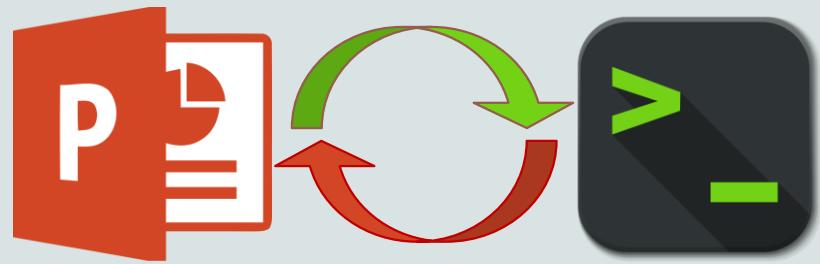
```
MyHelloObject::MyHelloObject(const Params &params) :  
    SimObject(params), myName(params.name),  
    latency(params.time_to_wait),  
    timesLeft(params.number_of_fires)  
{ ... }
```

**params:** provides interface to the parameters *declared* in the python SimObj description

**Name** and other variables are available for all SimObjects

Enough time? Add more parameters

**Switch!**



# Questions?

We covered

How to build a SimObject

How to schedule events

Debug statements in gem5

Adding parameters to SimObjects

# Interacting with memory

*[https://www.gem5.org/documentation/  
learning\\_gem5/part2/memoryobject/](https://www.gem5.org/documentation/learning_gem5/part2/memoryobject/)*

# Sending and receiving requests

Communication with “Packet” which has a “Request”

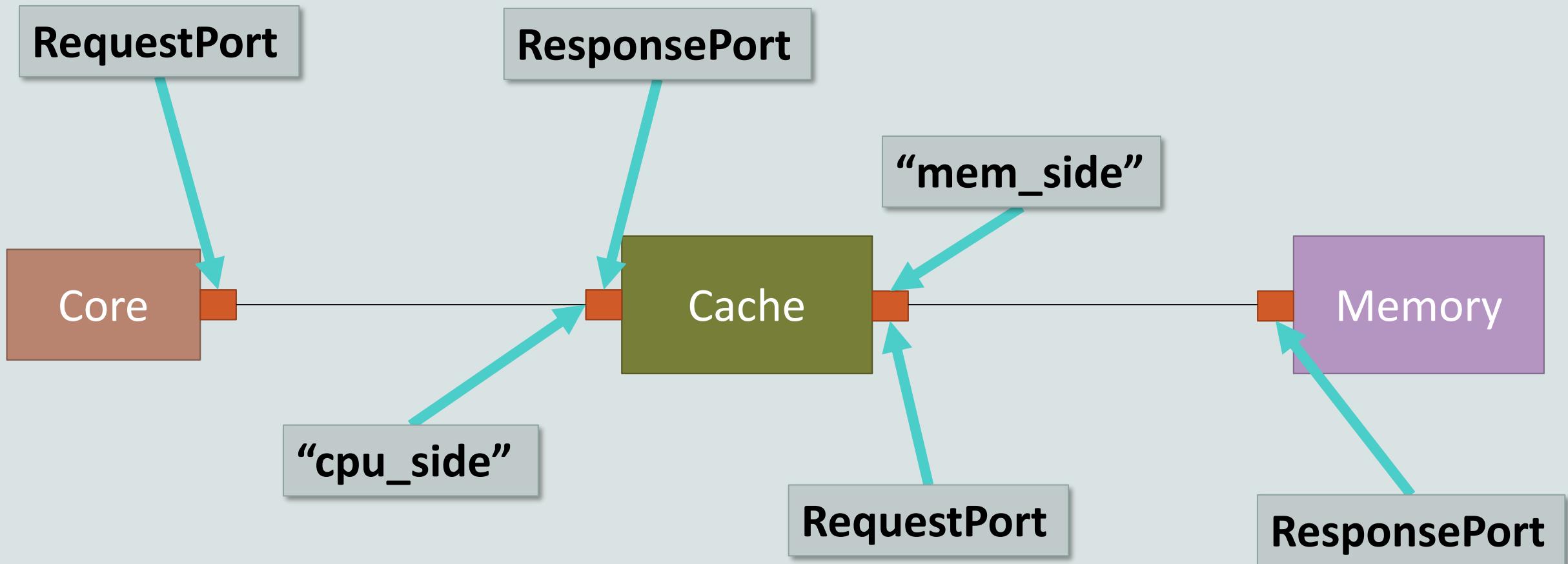
**Ports** -> Interface to connect SimObjects

**Requestor** -> sends requests, receives responses

**Responder** -> receives requests, sends responses

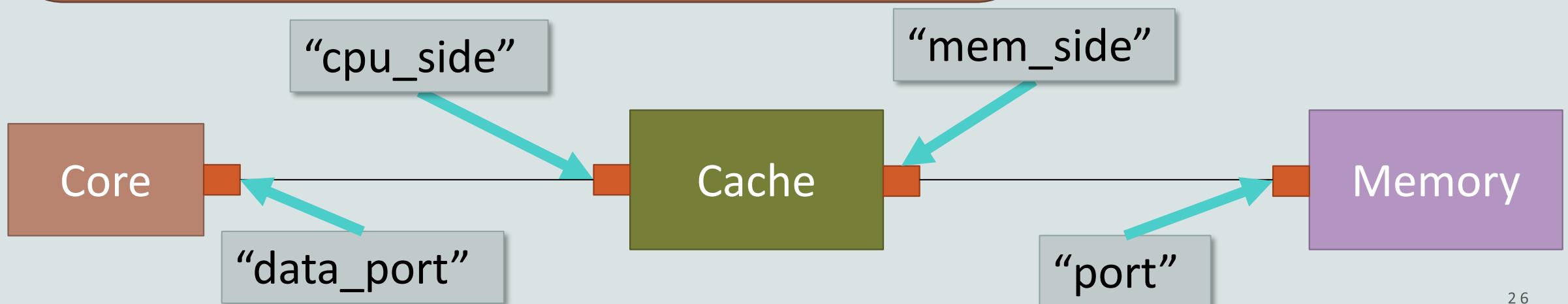
Also: CPU-side vs Memory-side

# Example of ports



# Ports are connected in python config

```
| ...
| system.memory = MemCtrl()
| system.cpu = TimingSimpleCPU()
| system.cache = Cache()
| ...
| system.cpu.data_port = system.cache.cpu_side
| system.cache.mem_side = system.memory.port
| ...
```



# Packets

Unit of transfer between SimObjects

Packets pass between Requestor and Responder ports

Packets have

Request

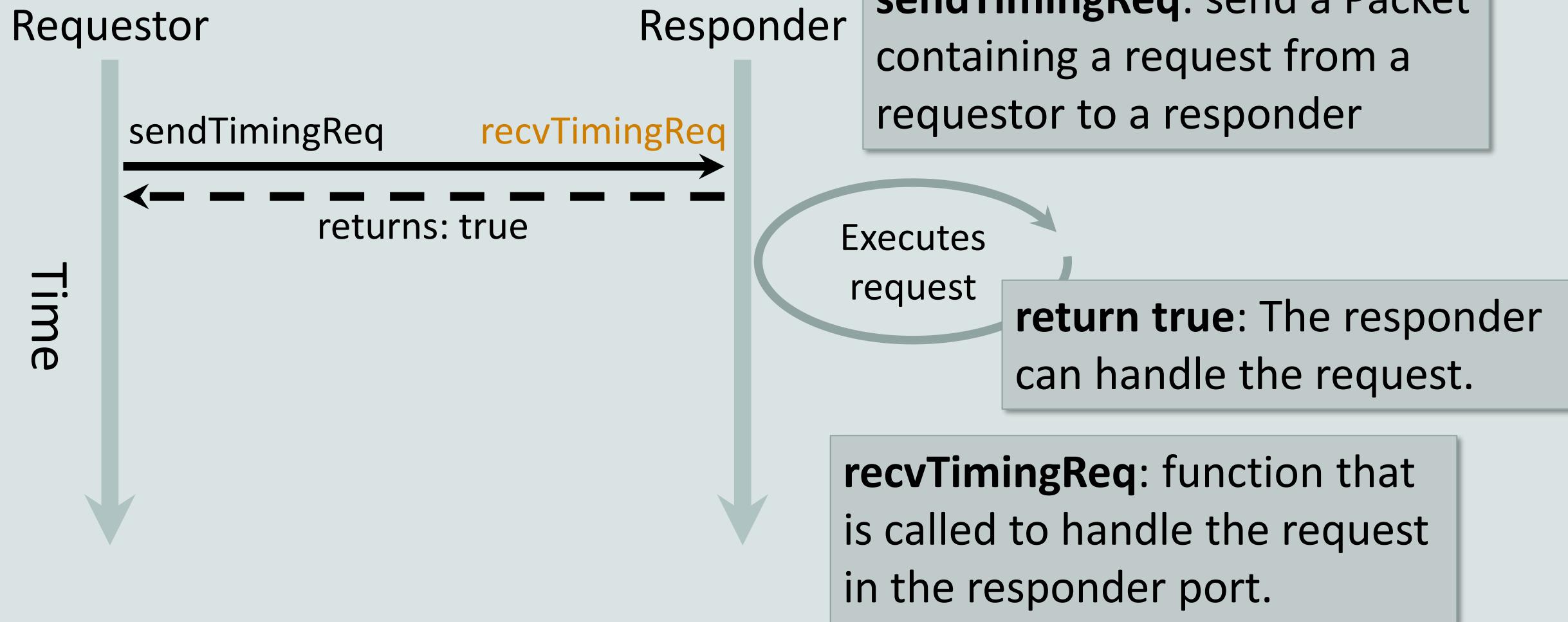
Command

Data

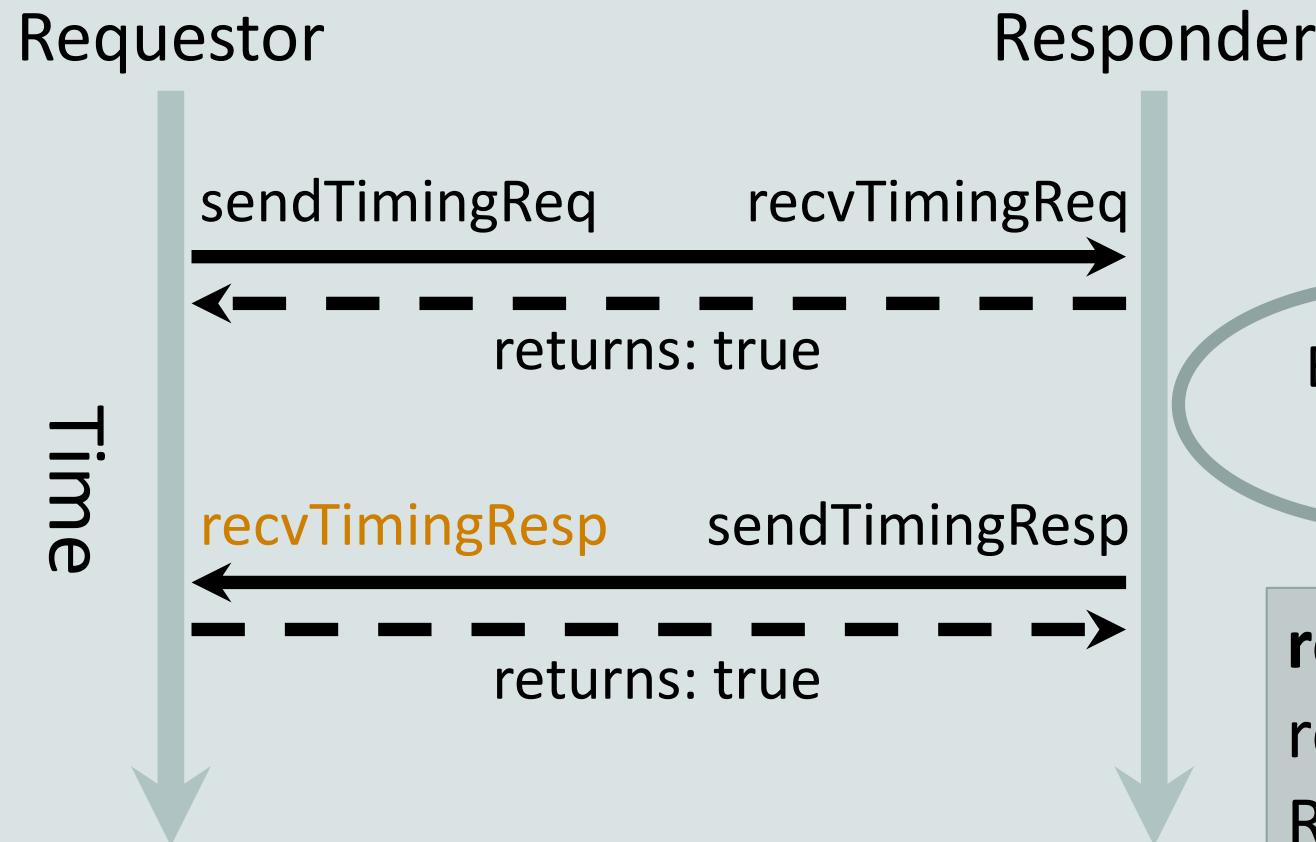
Much more...



# Requestor and responder ports



# Requestor and responder ports

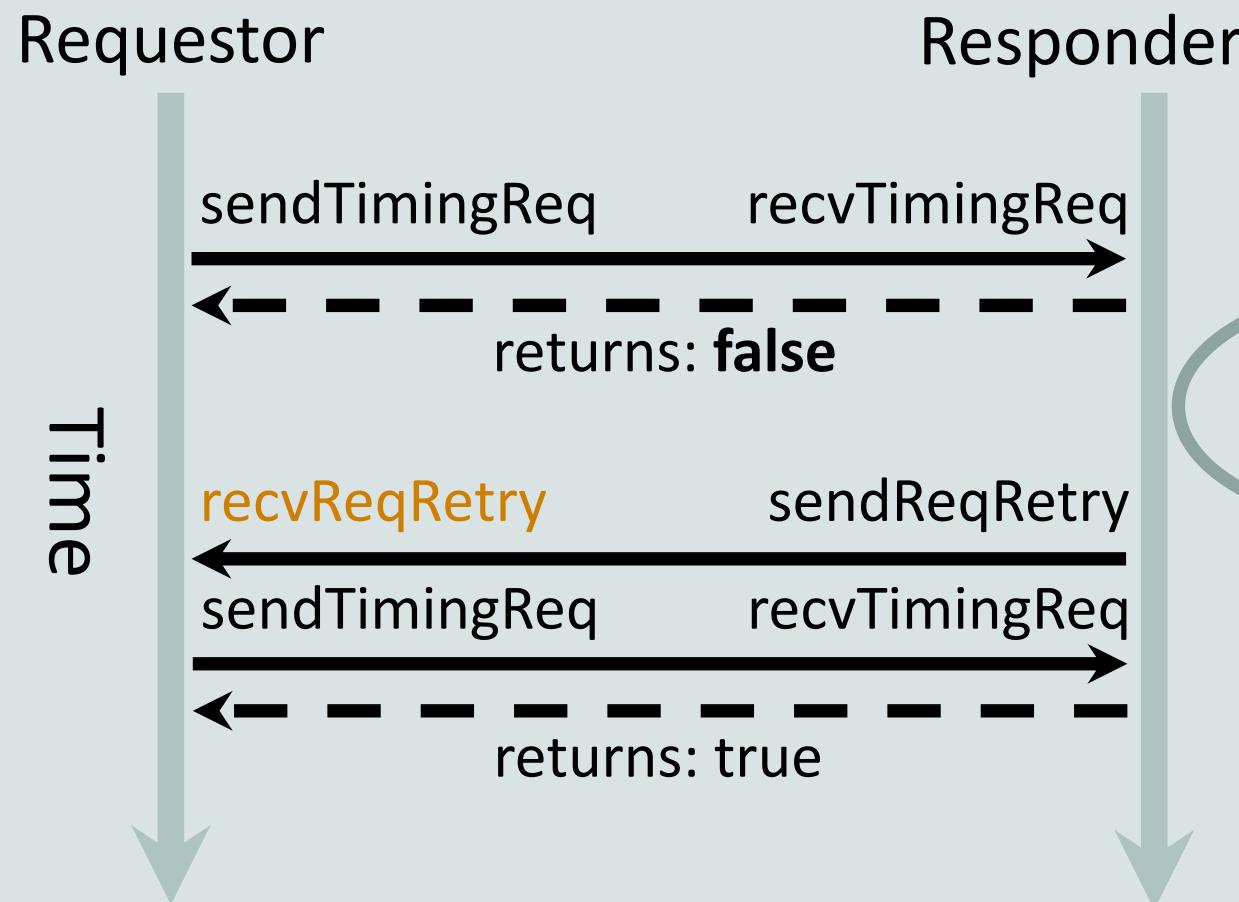


**sendTimingResp:** The responder finishes processing the request, and now sends a response (same packet).

Executes request

**recvTimingResp:** Handles the response from the Responder. Returning true means the packet is handled.

# Requestor and responder ports



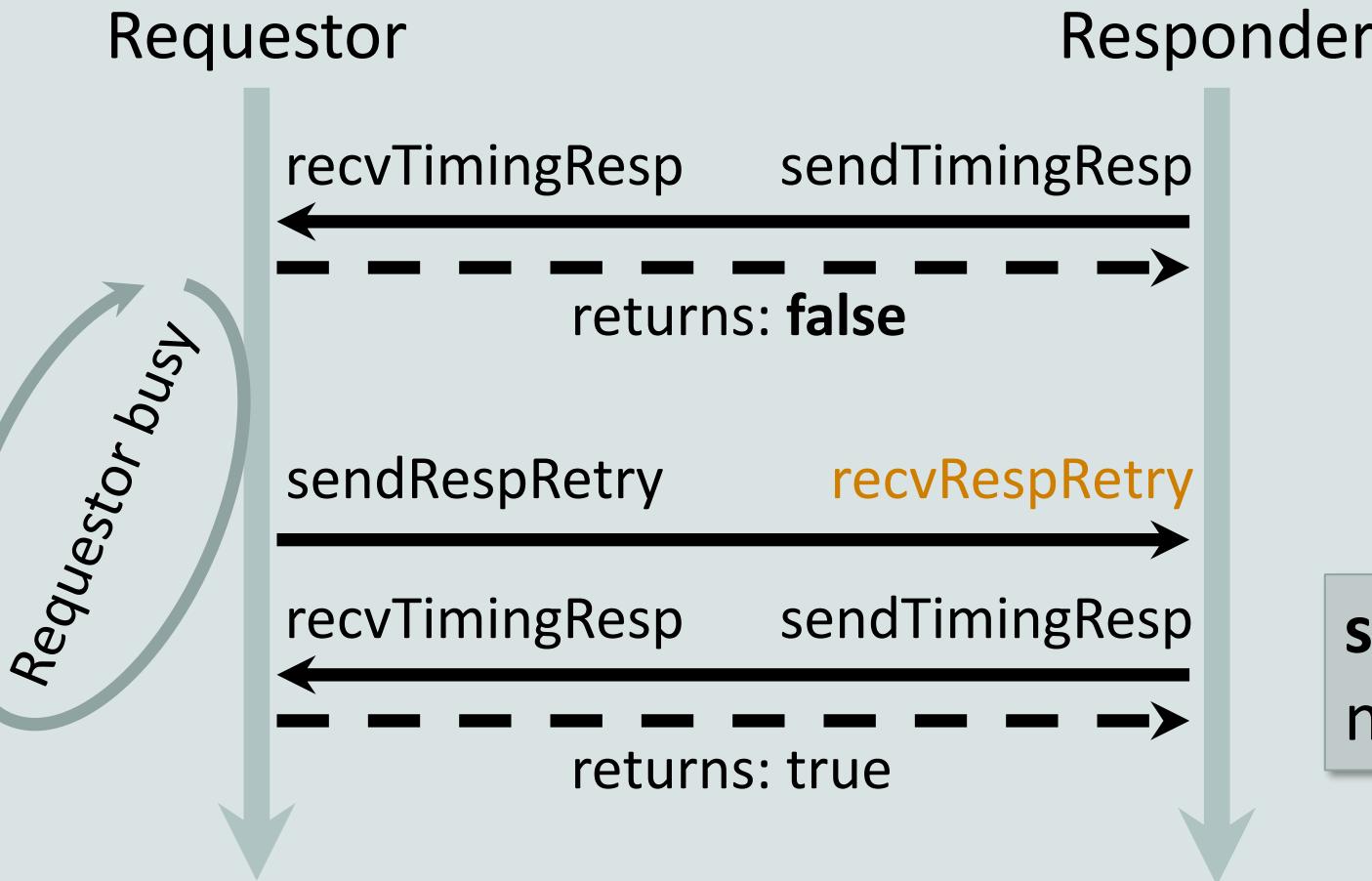
**return false:** Responder cannot currently process the Packet. Resend the packet later. The **Requestors's responsibility** to track Packet.

Responder  
busy

**recvReqRetry:** Can now retry the request by calling `sendTimingReq`.

**sendReqRetry:** Tell the requestor it can retry the stalled Packet.

# Requestor and responder ports



**return false:** Requestor cannot currently process the Packet.  
Resend the packet later. The **Responders's responsibility** to track Packet.

**sendRespRetry:** Responder can now retry the response.

# Requestor and responder ports

## Requestor

recv Timing Resp

recv Req Retry

recv Range Change

## Responder

recv Timing Req

recv Resp Retry

recv Functional

get Addr Ranges

# Questions?

Requestor/Responder ports

Configuring memory systems

**Next up:** Some examples of current memory models & more